Sensorimotor neuroprosthetics

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Cursus

<table>
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<tr>
<th>Course</th>
<th>Sem.</th>
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<tr>
<td>Bioingénierie</td>
<td>MA1, MA3</td>
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<td>Mineur en Neuroprosthtiques</td>
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<td>Mineur en Neurosciences computationnelles</td>
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<td>Mineur en Technologies biomédicales</td>
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<td>Neurosciences</td>
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<td>Sciences du vivant</td>
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Language: English  
Credits: 4  
Session: Winter  
Semester: Fall  
Exam: Oral  
Workload: 120h  
Weeks: 14  
Hours: 4 weekly  
Lecture: 2 weekly  
Exercises: 2 weekly

Remarque

MA3 only

Summary

Teaching objectives: history, neural control of movement, computational motor control, neurorehabilitation after CNS disorders, upper limb and hand neuroprostheses, lower limp neuroprostheses, student project.

Content

*History:* Emergence of the field of neuroprosthetics, current evolution of neuroprosthetics towards enabling systems for neurorehabilitation, entrepreneurial opportunities and challenges.  
*Neural control of movement:* organization of supraspinal and spinal neuronal systems underlying the production of locomotion, reaching and grasping. Disease specific alteration of neural control processes after CNS disorders and limb amputation.  
*Computational motor control:* General principles associated with the production of movements, analysis of kinetics, kinematics, muscle synergy, ensemble cortical modulation, internal models, finger enslavement.  
*Neurorehabilitation after CNS disorders:* basic principles underlying learning and plasticity in the CNS, impact of neurorehabilitation on the recovery of sensorimotor functions, activity-dependent reorganization of neuronal circuits, practical use of neuroprosthetic systems for neurorehabilitation in animals and human.  
*Upper limb and hand neuroprostheses:* current strategies for the development of neuroprosthesis for the restoration of reaching and grasping in specific types of motor disorders such as stroke, spinal cord injury, and amputation. (1) neurocontrolled hand prostheses; (2) invasive and non-invasive neuroprostheses based on neuromuscular electrical stimulation; (3) robot-based neuroprostheses.  
*Lower limb neuroprostheses:* current strategies for the development of neuroprosthesis for the restoration of walking in severely paralyzed people. (1) neurocontrolled full body exoskeleton; (2) invasive and non-invasive electrical neuroprostheses; (3) invasive electrochemical neuroprosthesis; (4) Hybrid neuroprosthetic system.  
*Student project:* Approximately half of the course will involve a group project in which the students will conceive their own neuroprosthetic system

Keywords

Neuroprosthetics; grasping; reaching; locomotion; robotics; epidural electrical stimulation; FES

Learning Prerequisites

Required courses  
*Only for second year master students and PhD students following the program in Neuroscience*

Learning Outcomes

By the end of the course, the student must be able to:
• Differentiate the basic principles underlying the neural control of locomotion, reaching, and grasping in healthy and disabled subjects
• Develop a broad view on existing neuroprosthetic systems, and should be able to identify current limitations and challenges for future applications.
• Identify the conceptual and practical bases for the development of a novel neuroprosthesis (group project)

Teaching methods
The students will get scientific background by the two teachers, they will be involved in hands-on activities and will also have to work on scientific projects to conceive their own neuroprosthetic system

Assessment methods
Oral exam during the session