

ENG-615

Topics in Autonomous Robotics

Alahi Alexandre, Aloui Omar, Bouri Mohamed, Floreano Dario, Ijspeert Auke, Micera Silvestro, Paik Jamie, Zamir Amir, Shea Herbert

Cursus	Sem.	Type
Robotics, Control and Intelligent Systems		Opt.

Language of teaching	English
Credits	4
Session	
Exam	Project report
Workload	120h
Hours	56
Courses	32
TP	24
Number of positions	25

Frequency

Every 2 years

Remark

March 18 - 14:00 to 18:00 April 15 - 14:00 to 18:00 April 20 - 13:30 to 17:30 April 27 - 13:30 to 17:30 May 4 - 13:30 to 17:30 May 10 - 9:00 to 13:00 May 19 - 9:00 to 12:00 May 26 - 9:00 to 12:00

Summary

Students will be introduced to modern approaches in control and design of autonomous robots through lectures and exercises.

Content

- Thursday March 18, 14:00 to 18:00 - Locomotion control in swimming and legged biorobots - Auke Ijspeert
- Thursday April 15, 14:00 to 18:00 - Tensegrity Robotics - Dario Floreano and Omar Aloui
- Tuesday April 20, 13:30 to 17:30 - Visual perception for robotics - Amir Zamir
- Tuesday April 27, 13:30 to 17:30 - Soft electrically-driven actuators for robotics and haptics - Herb Shea
- Tuesday May 4, 13:30 to 17:30 - Deep learning for Autonomous Vehicles - Alexandre Alahi
- Monday May 10, 9:00 to 13:00 - Robotics for Rehabilitation and Assistance - Mohamed Bouri
- Wednesday May 19, 9:00 to 12:00 - Design and Control of Prosthetic Devices - Silvestro Micera
- Wednesday May 26, 9:00 to 12:00 - Reconfigurable robotics - Jamie Paik

Keywords

Evolutionary Mobile Robotics Modular Locomotion, Human-robot, Interaction, Mobile Robot Design

Resources**Moodle Link**

- <http://moodle.epfl.ch/course/view.php?id=252>